

6 Apply (7) to $m = 6 \text{ mm}$

$$\frac{v}{s} = \max\left(-0.5, \frac{30-19}{40}\right) = 0.275 \quad \therefore \frac{v}{s} = 0.275 \times 6 = 1.65 \text{ mm}$$

$$\frac{1}{s} = 0.6 \quad \Rightarrow \quad \frac{1}{s} = 0.6 \times 6 = 3.60 \text{ mm}$$

Without profile shift

pitch dia $D = mz = 6 \times 19 = 114 \text{ mm}$

base \odot dia, $D_0 = D \cos 20^\circ = 107.1 \text{ mm}$

and is "basic", no matter what profile shift.

With profile shift of 0.4

extended pitch dia, $D' = D + 2ms = 118.8 \text{ mm}$

$\&$ addendum dia = $D' - 2mb$

= $118.8 - 2 \times 6 \times 1.25 = 103.8 \text{ mm}$

dedendum dia = $D' + 2mz = 118.8 + 2 \times 6 \times 1 = 130.8 \text{ mm}$

The base pitch is the distance around the base \odot circumference from one tooth to the next.

$p_0 = \pi D_0 / z = \pi \times 107.1 / 19 = 17.71 \text{ mm}$

From the worked example, for unit module:

$\gamma = (\frac{1}{2} + s \tan \alpha) / R + \tan \alpha - \alpha$

= $(\frac{1}{2} + 0.4 \tan 20^\circ) / \frac{1}{2} \times 19 + \tan 20^\circ - \frac{\pi}{180} \times 20$

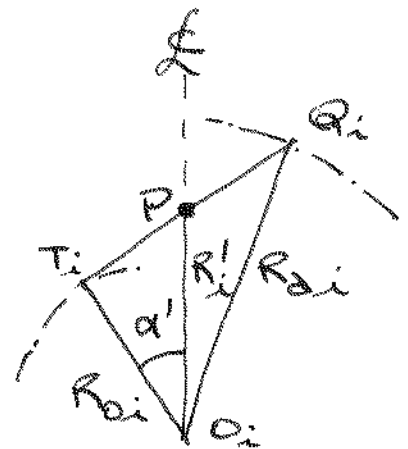
= $0.1129 \text{ rad } (6.47^\circ)$

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The contribution of the i th mating gear to the path of contact is:

$PQ_i = T_i Q_i - T_i P \quad ; i=1,2$

= $\sqrt{(R_{ai}^2 - R_{oi}^2)} - R_i' \sin \alpha'$



So, for the two gears, the length of the path of contact:

is:

$Q_1 P Q_2 = \sum \sqrt{(R_{ai}^2 - R_{oi}^2)} - \sum R_i' \sqrt{1 - \cos^2 \alpha'}$

where, for unit module:

$R_{ai} = R_i + s_i + a = \frac{1}{2} z_i + s_i + 1$

$R_{oi} = R_i \cos \alpha = \frac{1}{2} z_i \cos \alpha$

$\sum R_i' = c = \frac{1}{2} \sum z_i + \sum s_i$ from (9)

$\cos \alpha' = \sum R_{oi} / c = \frac{1}{2} \sum z_i \cos \alpha / c$

So $E_f = 2 Q_1 P Q_2 / 2\pi \cos \alpha$ from (6)

$$2\pi \cos \alpha \cdot E_f = \sum_{i=1,2} \sqrt{[(z_i + 2(1 + s_i))]^2 - (z_i \cos \alpha)^2} - \sqrt{[(\sum z_i + 2 \sum s_i)^2 - (\sum z_i \cos \alpha)^2]}$$