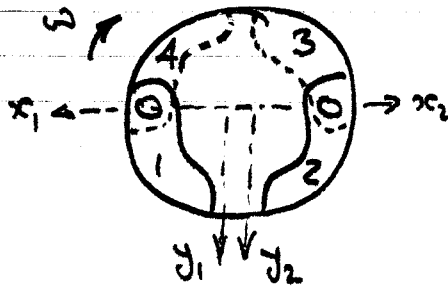
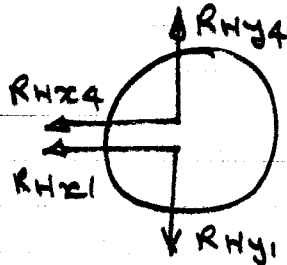


from the lower two: -



Suppose  $\omega$  is clockwise.  
Shoes 1 & 3 behave identically -  
they are both leading  
Shoes 2 & 4 are both trailing.

Having got results for 1 & 2 from  
program display, we use results  
of 2 in 4 to find LH-hinge  
reaction. Thus rotating 2:



$$R_{Hx} = R_{Hx1} + R_{Hx4} = R_{Hx1} + R_{Hx2} = -991 - 209 = -1200 \text{ N}$$

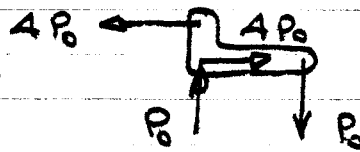
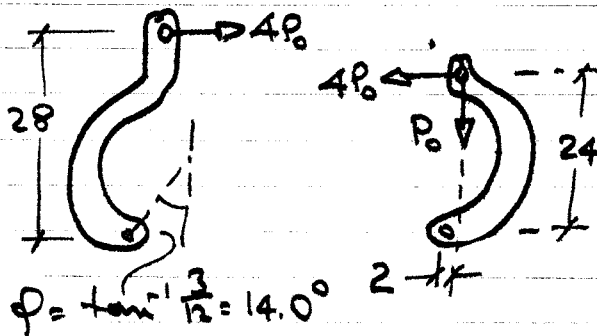
$$R_{Hy} = R_{Hy1} - R_{Hy4} = R_{Hy1} - R_{Hy2} = 14910 - 6090 = 8820 \text{ N}$$

whence  $R_H = 8901 \text{ N}$ .

The torque of the brake will be twice that of the  
two lower shoes, i.e. 2646 Nm.

By symmetry it is readily shown that the drum  
shaft reaction vanishes.

5.



Analysis of the bell  
crank demonstrates  
that the forces must  
be as shown.

The LH shoe is straight forward

$$\theta_1 = 20 - 14.0 = 6.0^\circ \quad \theta_2 = \theta_1 + 130^\circ = 136.0^\circ$$

shoe/brake actuation force ratio = 4

The RH shoe needs consideration for program input.

The actuation force ratio =  $\sqrt{4^2 + 1^2} = 4.123$

The moment arm of the shoe actuation force, 'e', is

$$4.123e = 4 \times 24'' - 1 \times 2'' \Rightarrow e = 22.8''$$

The inclination of the shoe

actuation force is:

$$\theta_p = 90^\circ + \tan^{-1} \frac{P_0}{4P_0} - \phi = 90^\circ$$

Hence the program input.



6. As (5) but superior so lining measure more nearly  
the same for the two shoes.